

# Design of an Image Generation Truth Model for Testing Attitude Determination Algorithms for a Star Tracker

Master of Science in Aerospace Engineering

Adrianna Y. Fukuzato

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The Designated Project Committee Approves the Project, Titled

DESIGN OF A NEW GENERATION OF MULTIMEDIA COURSEWARE

FOR THE BACCALAUREATE PROGRAM IN BUSINESS ADMINISTRATION



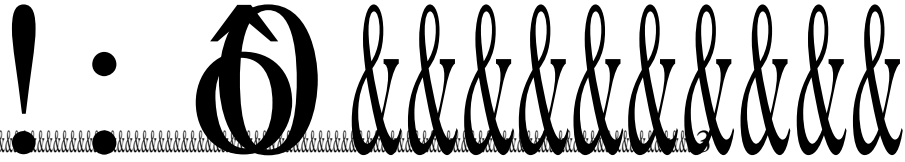


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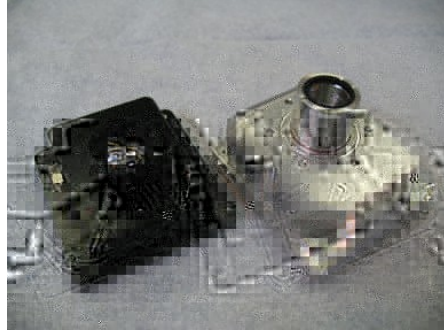
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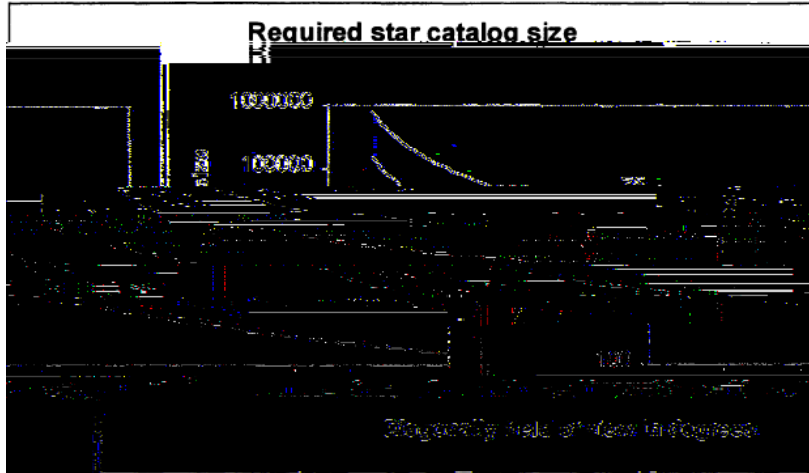


Figure 1-3:

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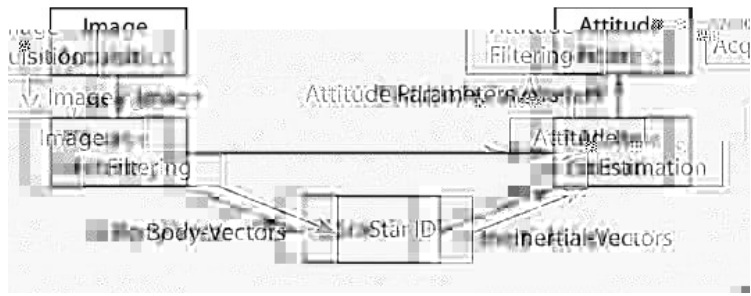


Figure 1-4: Typical Attitude Estimation for Star Trackers [1]

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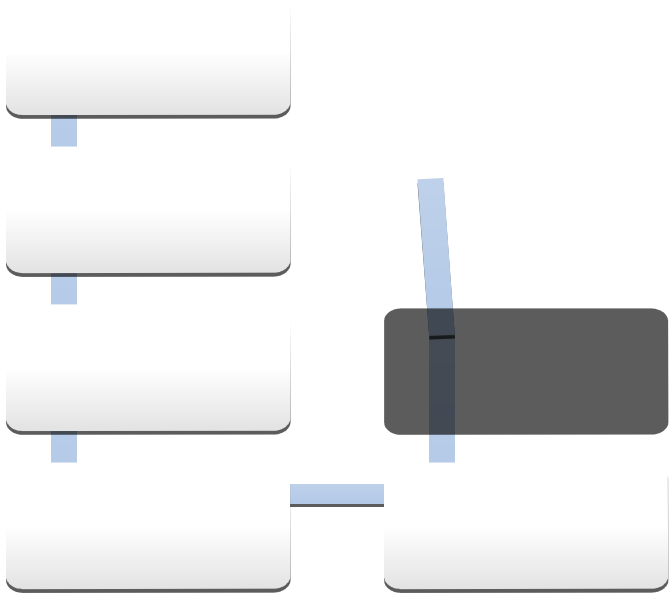
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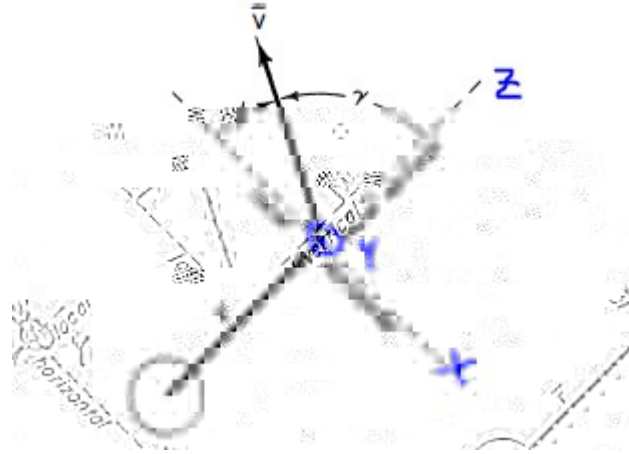


Figure 4- , : Local -ertical Local . ori/o"tal spacecra#t re#ere"ce #ra ! e [10]

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$$\phi(x + y) = \phi(x) + \phi(y)$$

$$\phi(\alpha x) = \alpha \phi(x)$$
 where  $\alpha \in \mathbb{R}$ .

## 1. Quaternions

Let  $A$  be a real algebra. A quaternion is an element of  $A$  of the form
 
$$a + bi + cj + dk$$
 where  $a, b, c, d \in \mathbb{R}$  and  $i, j, k$  are elements of  $A$  satisfying
 
$$i^2 = j^2 = k^2 = -1$$

$$ij = -ji = k$$

$$jk = -kj = i$$

$$ki = -ik = j$$

The most general displacement of a rigid body about a fixed point is a rotation about some

axis. Let  $\mathbb{H}$  be the algebra of quaternions. A rotation about a fixed point can be represented by a quaternion  $q$  acting on a vector  $v$  as
 
$$v \mapsto qvq^{-1}$$
 where  $q$  is a unit quaternion, i.e.  $qq^{-1} = 1$ .

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Table 1: Project design reference parameters

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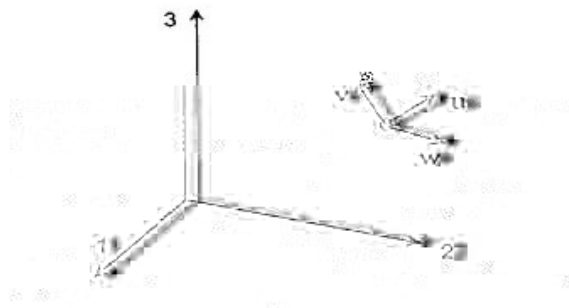
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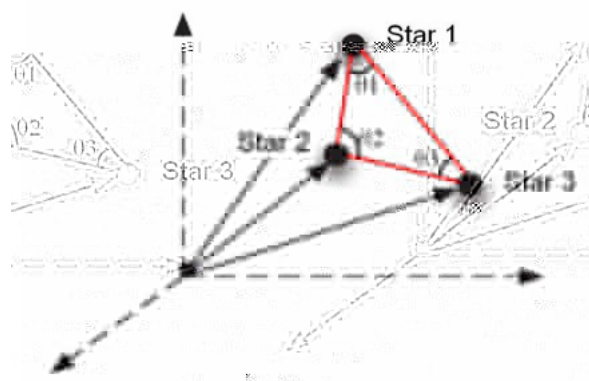
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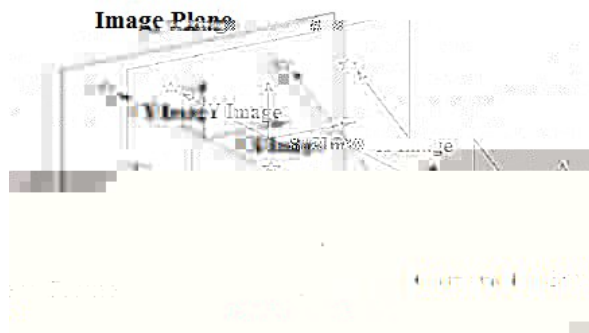
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Figure , -6

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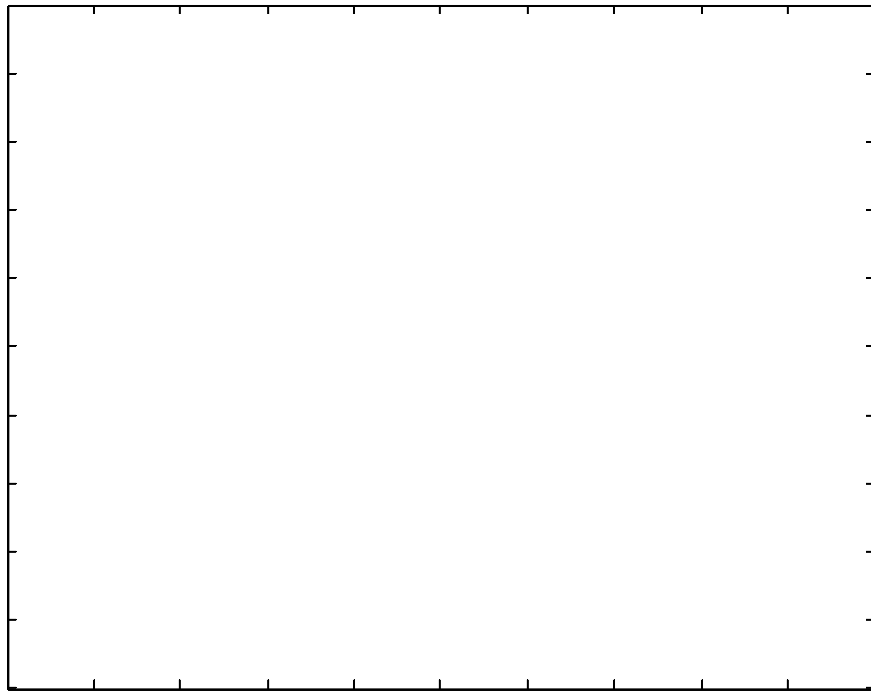
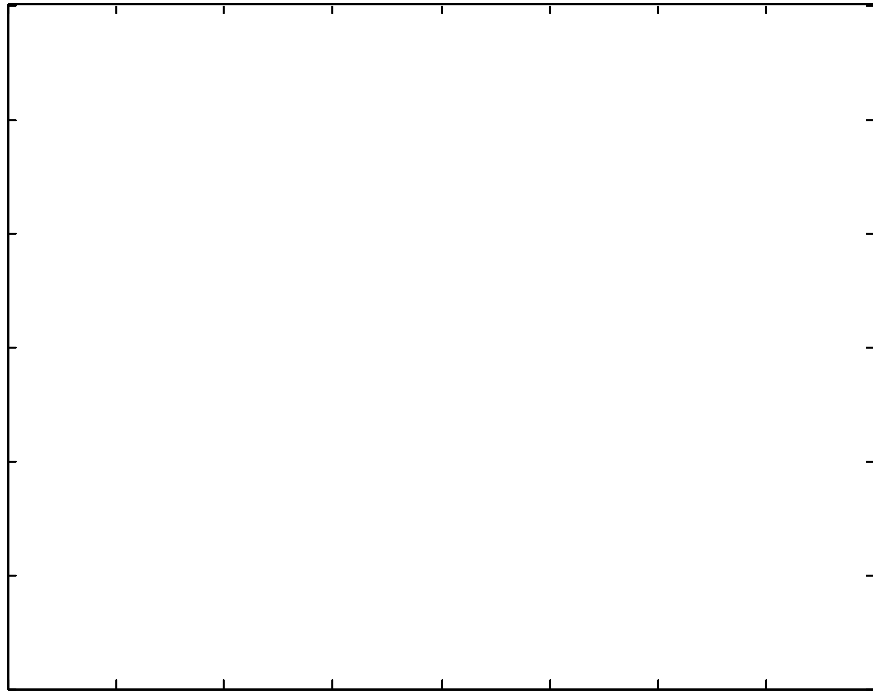


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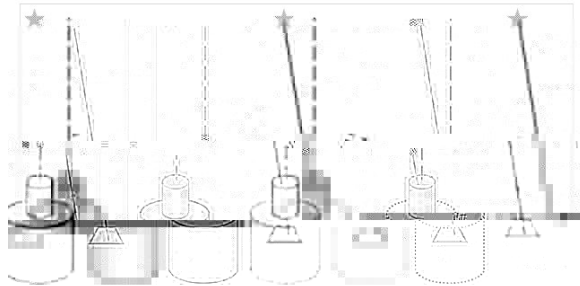


Figure ; -12: Pi''ole ! odel [2]

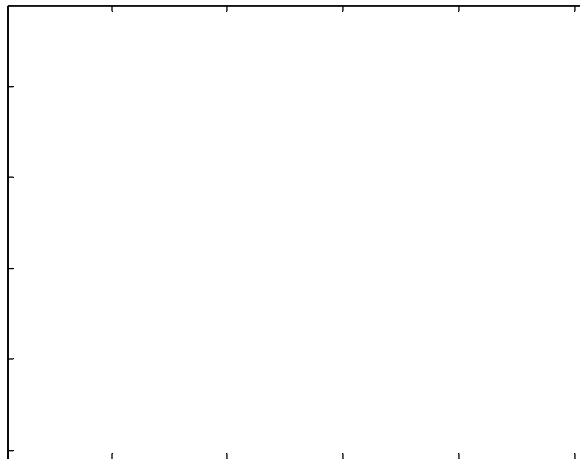


Figure ; -13: \*aussia'' Star istt ! á t! tãp



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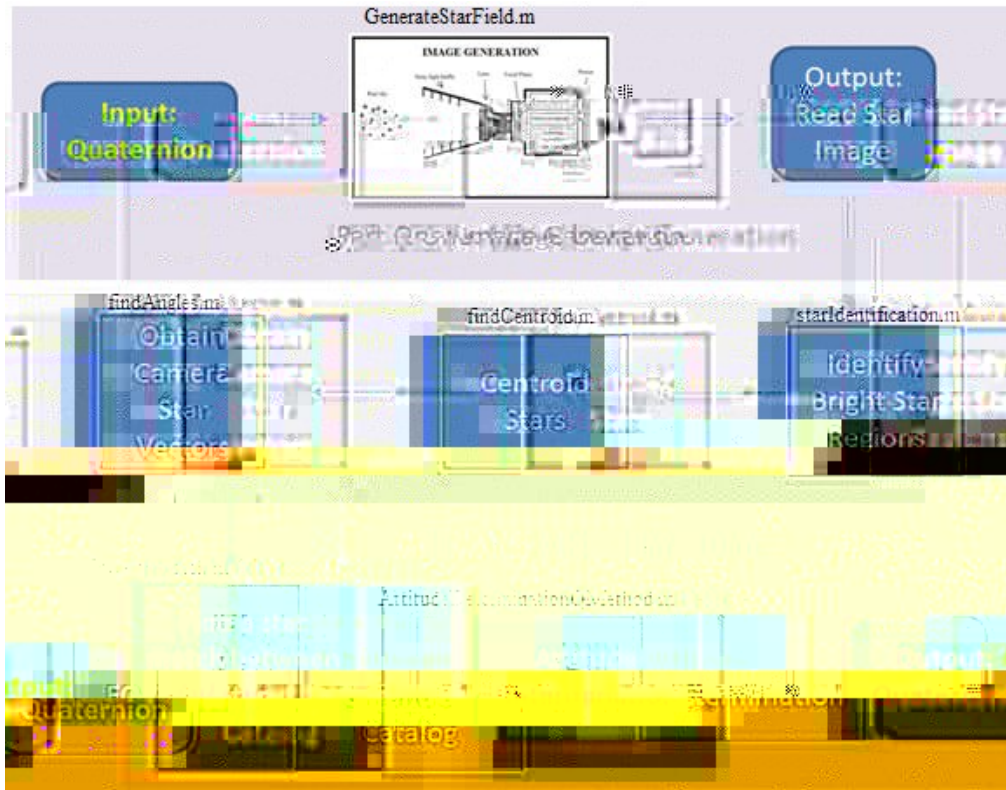


Figure 10-14: Star Tracker +ode @lock iagra!

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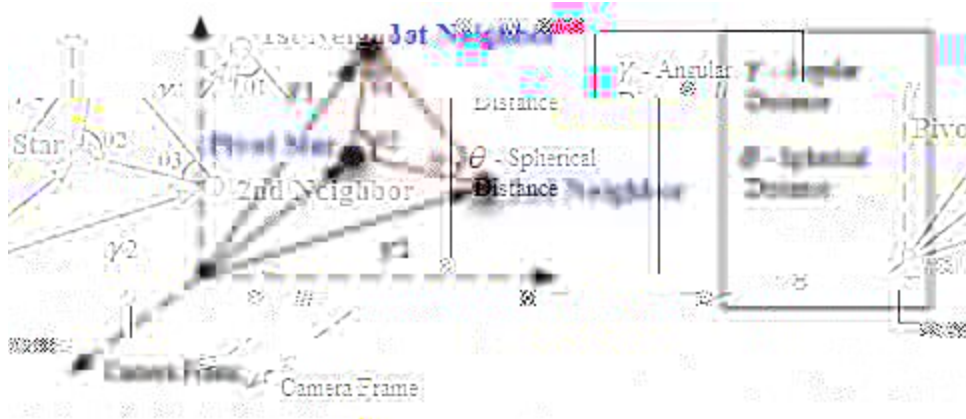


Figure 10-1 ( : T%ree stars #or ! a Tria"ngular Feature 7TF8

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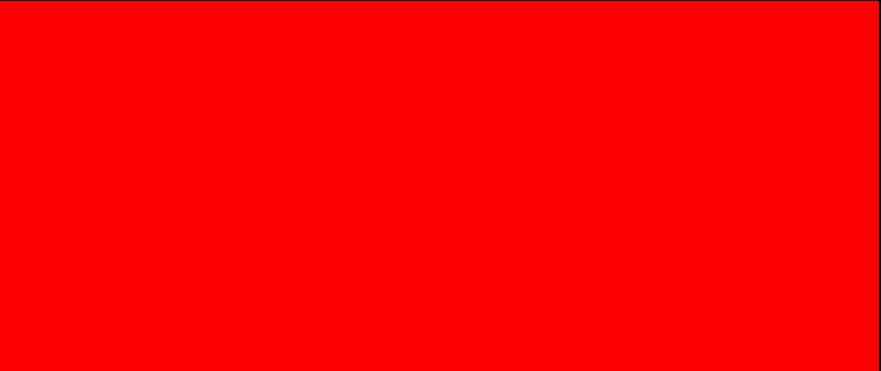
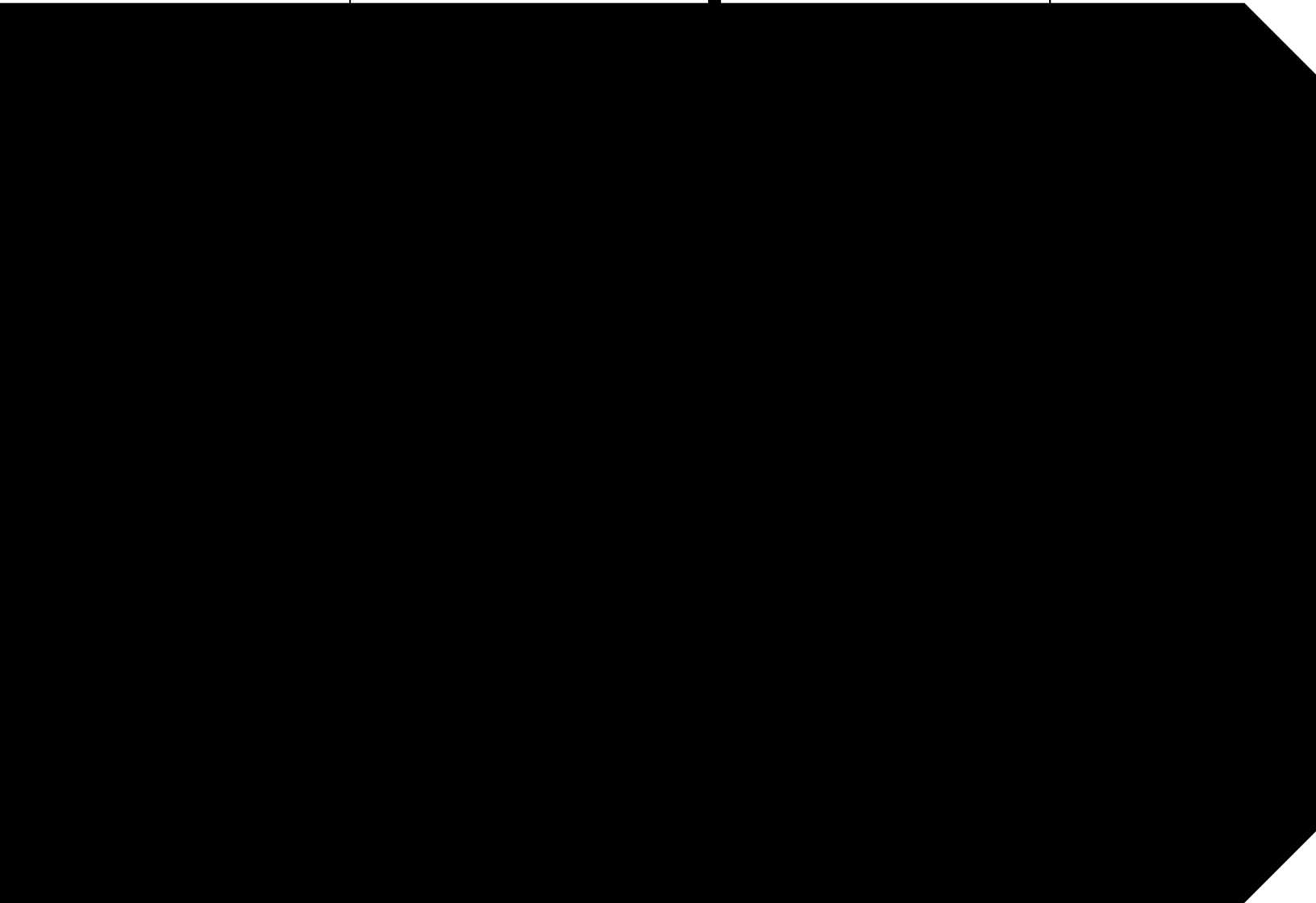
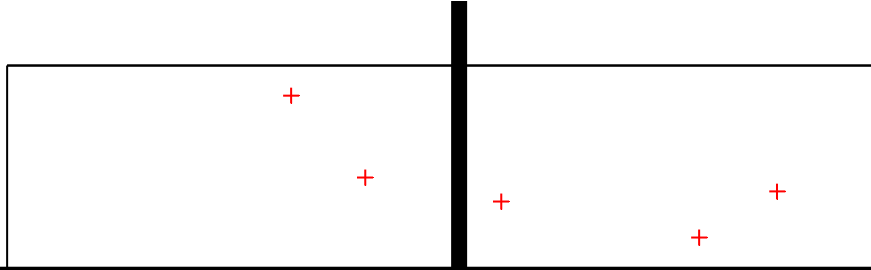
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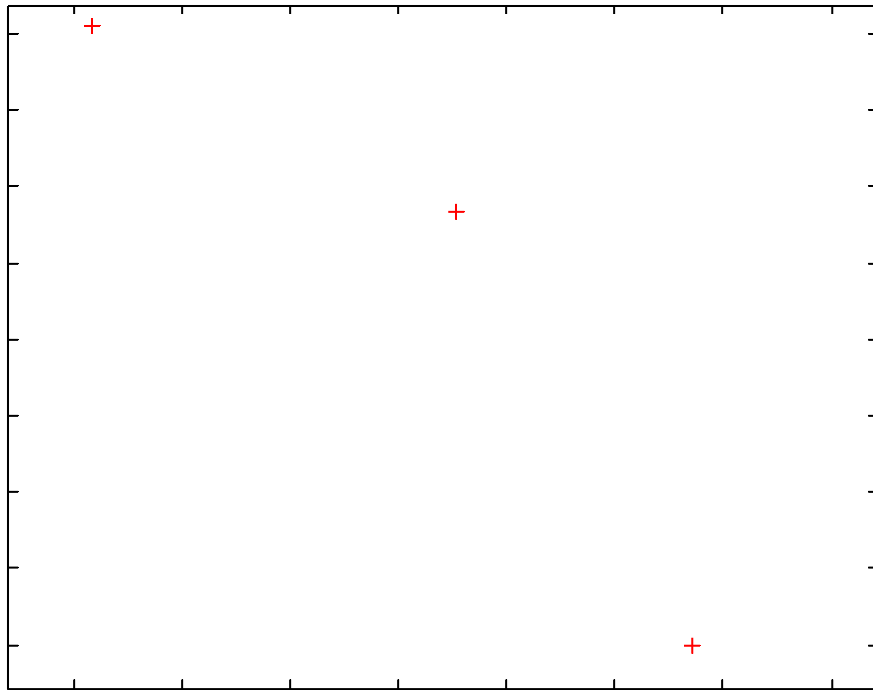


Figure 10-1, : Tria "gular Feature a#ter Star ? atc%i"g

### "=.\$ Attitude Determination

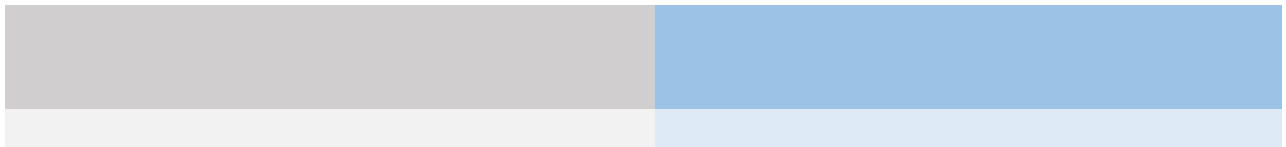
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\$#

! #%

!?

& \*+(

& '

\$ ! %



5.\$: const•? 6s•? Dm

?

J 5 @ ?  
@

\*@ + & @ 3@ \$J5@ %

J 4-4 & \*J\$3%C36J\$4%C36J\$=%C3/J\$'%C3 3 \$J\$3% J\$4%/J\$=% J\$'%% 3 \$J\$3% J\$=%6  
J\$4% J\$'%%(!!!

3 \$J\$4% J\$3%6J\$=% J\$'%% 6J\$3%C3/J\$4%C36J\$=%C3/J\$'%C3

3 \$J\$4% J\$=%/J\$3% J\$'%%(!!!

3 \$J\$=% J\$3%/J\$4% J\$'%% 3 \$J\$=% J\$4%6J\$3% J\$'%% 6J\$3%C36  
J\$4%C3/J\$=%C3/J\$'%C3+( .

@ & J 4-4 \$@ #%(

### C.+: CameraStarCoordinates.m

# H @

?

J 5 " 5 . 5 5 ?  
@. 5 @ 3@

H

. & \$J5 %

H @ & !H @(

\$# ? ! #%

@. & @. \$J%(

. & \*+(

7 & '(

&' \$ ! %

L & \$ !? \$ 5 %%(

f . ! d ° \$L5@. % & \$H @%5

. ! \$75 % & ! \$ 5 %(  
. ! \$75 % & ! \$ 5 %(  
. ! \$75 % & ! \$ 5 %(  
. ! \$75 % & ! \$ 5 %(  
. !. \$75 % & !. \$ 5 %(  
. ! \$75 % & ! \$ 5 %(  
. !? \$75 % & !? \$ 5 %(  
!#

!#

```

@      &      .      !?      $ 5 %(
@      & @      3@      $J5@      %(
      .      !      $ 5 % & @      #(

```

## C.: Camera\$(i/eIS-ace.m

```

                    5 -515F
                    A -
* 5 + &      3A -      $      5 -5 15 F%
&      ! (
&      ! (
I &      !I(
@ &      !@(
& $ID3%/'(
& $@D3%/'(
& D F(
& 6 $ - %D (
& 6 $ 1 %D (

```

## C.2: (i/eIS-aceCoordinates.m

```

                    7 # H @
                    5
                    .
H      I      3A -      "      -
      .      & A -      $J5      5      .      %
&      &      .      !      (
&      $      %(
& '
* 5 + &      3A -      $      5      $ 5'%5      $ 53%5      $ 54%%(
      .      !A -      $ 5'% & (
      .      !A -      $ 53% & (

```

### C.3: )ohnson8cur#e.m

M @  
\$ DD . ! ! D .D D D 8'!@L%  
N I 1  
" 5 M @

\* . 5M@ + & L @ \$%

. & \$9 9 4988% ' 6:(  
& F \$<:5'%(  
. & F \$99:5'%(  
>&\*8!883!33! 8 8 &\*8)883!33! 8 8 &\*8)883!33! 8 8 3;rIHRS 8 &\*!883!33! 8 8

```

8!8=3
8!84;
8!849
8!84
8!83<
8!834
8!8':
8!8'
8!8'=
8!8'3
8!88:+(
M@      & *      ( > ( .      +(

```

### C.3: ref@star.m

```

- " . E A
H L # @ - 5 1 7 0 # "
- & $%
& ! 3 '8C64=( *M + A 7#
7 & '!4<8 9 '8C634( *MDP+ G F #
& 3!::; '8C<( * D +
N & 9;;;( *P+
>I & '=:9:;<;'888( * + > I
, & :9<88888( * + #
& $>ID, %C3( DD ! ! D D D FF 7DA 1 6
Q D 8=636 !
* . 5 M@+ & L @ $%(
& $$3 C3%!D$ . !C9! $ - $$ %!D$ . ! 7 N%%6'%%%#(
- & F$ . 5 ! M@%( # *OD 3+
- & $ -D %( ? # *OD 3D +
$ . 5 %
$# H -#%
- . $# R . * +#%
1 . $# *O D C3+#% O "$ . 5 ! M@5 N%(

```

### C.9: 58\$Tem-.m

```

0 G6@ -
G6@ -

```

N

N & G@3N \$. %

N & = 88 \$ 'D\$!:3 . / '!;% / 'D\$!:3 . /! 3% %(

### C."=: Aum(hotons.m

S6Q

```

      5      1      .      -      "
      @      5 G@      -5
H      L      @      5      .
*      .      5      + & E A      $@      5. 5      %
* 575 5 N5      + &      $%(
&      !      (
> &      !>(
*      .      5M@+ & L      @      $%(
N & G@3N $. %(
& $$$3      C3%!D$      .      !C9! $ - $$      %!D$      .      ! 7 N%%6'%%%%#(
&      (      *OD 3+ M@
&      F$      .      5 ! M@%(      *OD 3+
& 3!9'3C$63 !;6@      %(
? & $$      %!D      .      %#(
H - & $      D      %      !      (      *OD 3D +
H - & $$      D      %      !      %!D?(      *      D 3D +
&      H -      >(      *      +
$      H -%(
& $$$3      C3%!D$      .      !C9! $ - $$      %!D$      .      ! 7      N%%6'%%%%#(
$' %
$      .      5      5#. #%
$#      H - 6 ,      %#
$#@      & 63 !;#%
-      .      $#R      .      *      +%51      .      $#*O D      C3+#%
$3%
$      .      5      H -5# #%
$#      H -#%
$*#@      & #5      3      $@      %+%
-      .      $#R      .      *      +%51      .      $#*O D      C3+#%
O      "$      .      5      H -5N%(

```

C!

C.'': GenerateStar.m

"

5

1

A J

- " 5 " 5

5 - 5 @ 5

5 A - 5 0

H

\* 5 + & 0 H \$J%

& \$%(

. & \$J5 %(

& A - \$J5 5 . %()

I@ & !A - (

@ & ! (

. & !. (

I & !I(

@ & !@(

E F & !E F (

& F \$@5I%(

& \*+(

!I@ & I@(

! & ! (

! & @ (

! & ! (

& ' \$ I@%

& @ \$ %(

G@ & . \$ %(

& I@\$ 5' %(

& I@\$ 53%(

\* 5 5 + & 0 \$ 5G@5 5 5 %()

& /' /E F (

& /' /E F (

& 8 T )& '888(

& 8 T )& 3888(

\$ \$ %5 \$ %% & \$ \$ %5 \$ %% /

\$ 5 %()

5 " 1 # H @

\$ %(

\$ 1%(



A - -endi/ D: Algorithm Testing Matlab Files  
D.: findCentroid.m

```

H
75
$, %
S6 5
U6
* S5 U+ & $75 5, %
- & $, $ 5'%%(
1 & $, $'5 %%(
1 & F $ -5 1%(
- & F $ -5 1%(
& (
77 & ' -
& ' 1
1$775 % & , $775 % 7(
-$775 % & , $775 % (
& / '(
7 & 7 / '(
& (
U & $ 1$ %%D $, $ %%(
S & $ -$ %%D $, $ %%(

```

D.\$: starIdentification.m

```

$, %
" " !
O
Q -
5 # 5 ,
5 # , " " #
H
*, 5 + & $ %
&
E F & !E F (
- & 4(
Q0 & (
, & *+(
& '(

```

"L & 39(  
& 39 \$ Q0\$ 5'%%639(  
LL & "L \$ Q0\$'5 %%639(  
& (  
L & LL(  
Q0\$ 5L% & -  
L & '(  
L & '(  
& '(  
& '(  
3L & '(  
" Q0\$ 5L/'% & Q0\$ 5L%  
L & L / '(  
3L & 3L / '(  
" Q0\$ /'5L% & Q0\$ 5L%  
& / '(  
" & ( "L & L(  
" Q0\$ " 5 "L/'% V& 8  
"L & "L / '(  
L & L / '(  
"L && '  
. 7  
" & ( "L & L(  
" Q0\$ " 5 "L6'% V& 8  
"L & "L 6 '(  
L & L / '(  
"L && '  
. 7  
" & ( "L & L(  
" Q0\$ " 6'5 "L% V& 8  
" & " 6 '(  
& / '(  
" && '  
. 7  
" & ( "L & L( "  
" Q0\$ " /'5 "L% V& 8  
" & " / '(  
& / '(  
" && '  
. 7

, & \*# #5 3 \$ %+(  
, !\$ ,%! & Q0\$ 6 / 5L6 L L/ L%(  
, !\$ ,%! \$'5'% & 6 (

, !\$ ,%! \$'53% & L 6 L(  
, ! - \$ % & -\$ , !\$ ,%! \$ %%(  
Q0\$ 6 / 5L6 L L/ L% & 8(  
& / '(  
"L & 3L / L(  
"L & 39(  
& F \$ 6'53%(  
& ' 6'  
, & \*# #5 3 \$ %+(  
, & , !\$ ,%! (  
7 & , !\$ ,%! \$'5'%(  
& , !\$ ,%! \$'53%(  
\* S5 U+ & \$75 5, %(  
€

D.+: createStarCatalogDatabase.m

```

- #
5 A -
@ & A - 3 $ 5 A @ %
& $ !ID3%/'(
& $ !@D3%/'(
@ & F $45'%(
@- @F & $ 6 A @ $'%% ! D ! (
@1 @F & $ 6 A @ $3%% ! D ! (
@F & J $'6 @- @FC3 6 @1 @FC3%(
@- & @- @F @F(
@1 & @1 @F @F(
@ $'5' % & @-(
@ $35' % & @1(
@ $45' % & @F(

```

### D.3: findAngles.m

```

. "
- !
5
NH &
3
* @ 5 @ A - 5NH+ & > $ 5 %
& $ $(
& F $ $ %/35 $ %(
& ' $ %
' & * $ 5 % 6 ! D ! +#(
' & A - 3 $ 5 '%(
L & ' $ %
- & * $L5 % 6 ! D ! +#(
- & A - 3 $ -! )ß ö )ß ö < !Ⓣ

```

```

@      A -      & F      $454%(
@      A -      $ 5' % & *      E      .      6      ! D      !      + # (
@      A -      $ 53 % & *      6      ! D      !      + # (
@      A -      $ 54 % & *      E      .      6      ! D      !      + # (

@      & F      $454%(
& ' 4
@      $ 5 % & A - 3      $      @      A -      $ 5 % % (

```

```

NH & F      $ '54%(
@ ' &      @      $ 5' %(
@3 &      @      $ 53%(
@4 &      @      $ 54%(
' &      @      A -      $ 53% 6      @      A -      $ 5' %(
3 &      @      A -      $ 53% 6      @      A -      $ 54%(
> &      ° ! # $ é ö @ @ 6 2 R € $ @ 35 @ ' %(      & F      ñ % '5 3%(
G &      >      $ @ 35 @ 4 %(
&      >      $ '5 3%(
NH $ '5' % & > ' < 8D (
NH $ '53 % & G ' < 8D (
NH $ '54 % & ' < 8D (

```

## D.6: findStarMatch.m

```

H      .      "      H @
X      X      "
5
H @

```



```

P & *G/          $G% 6          $G% 1 $4% F(          $F%          $G%+(
*   @5   .   + &   $P%(
J   & *   @$=5=%(   @$' 45=%+(
      & $3      $   @$=5=%%% ' <8D (

```

## D."=: get 1 uaternion , rror.m

```

.                                     J          !
?                                     J          5 N          J
>                                     *          +
                                     ?          &          B          ?          $J          5J          %
J          & *J          $' % J          $=% 6J          $4% J          $3%(!!!
6J          $=% J          $' % J          $3% J          $4%(!!!
J          $4% 6J          $3% J          $' % J          $=%(!!!
6J          $3% 6J          $4% 6J          $=% J          $' %+(
J          & *6J          $3 =%( J          $' %+(
J          & J          J          (
                                     ?          & 3          $J          $=%%(

```

## D.""=: get ossFunction&alue.m

```

H                                     O . # .
@                                     . 1
                                     5 M
M &          H          @          $          @          5          @          %
. &          @          (
&          @          (
& ' (          "

```

>!



```

G & F      $454%(
G & F      $454%(
      & ' 4
      G &      . $ 5 %      $ $ 5 %%(
      G & G / G (

F & *G$354%6G$453%( G$45'%6G$'54%( G$'53%6G$35'%+(
P & *G/      $G% 6      $G% 1 $4% F(      $F%      $G%+(
* @5      . + &      $P%(      .      . $=5=%
      . - &      . $=5=%(
      . 8 &      /      /      (      "

M &      . 86      .      -( $      $J% P J%(

```

## D."\$: runMonteCarlo1 Method.m

```

'
      ? Q>N      J      5      !
J
      .      "
      ! N      "
B Q      J

```

```

, & *# #5 3 $ %+(
Q BQ !J!$, % & *J 0 J > +(
Q BQ ! !$, % & (
Q BQ !@ !$, % & * @ @ +(
Q BQ ! ? $ % & ? ( @ +(

```

### D.": calcMonteCarloAttitude , rror.m

```

E 5 Q BQ !
> 5 . 8 4 8 !

$#Q BQ ! #%
> ? & Q BQ ! ? (
F & F $'8885'%(
- & F $'8885'%(
L & '( 7 & '(

& ' $> ? %

& > ? $ %(
) '
F $L5' % & (
L & L / '(

'
7 & 7 / '(

F F & F 8(
F & F $ F %(
F & - 8(
- & - $ F %( 8 & 4 8

K & $F $ %% (
K & $F $ %% (
N - & $ - $ %% (
N - & $ - $ %% (

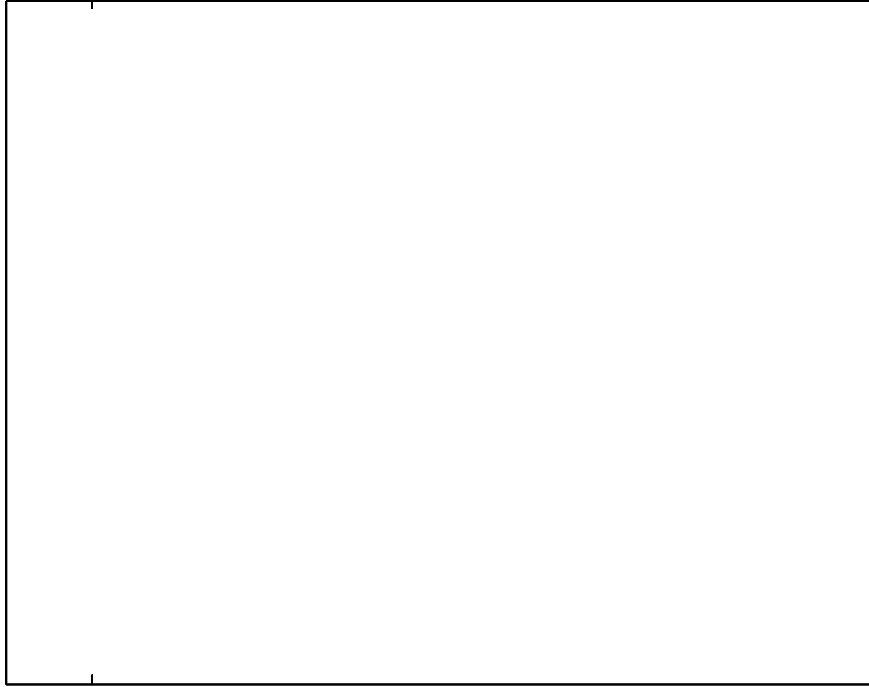
```

### D.": runScri-t@StarTrackerforAttitudeDetermination.m

```
N 7 > !
```

>D





,.\$ ,/am-le Star Identification B Star Matching \*ut-uts

