

Tentative Seminar Schedule

	TOPICS
	Course syllabus, pre-requisites, permit codes; course overview and structure
08/27, 08/29	Ch.1 Robotics History, Types, and Applications Ch.2 Robotics Terminologies, Configurations, and Workspace
Week #3 09/05	Ch.3 Homogenous Transformation Matrix and Robot Link/Human Arm Descriptions
09/10, 09/12	Ch.4a Coordinate Transformation Ch.4b Denavit-Hartenberg Convention to Assign Frames to Links

LAB INFORMATION

To enhance classroom learning and to provide the students hands-

